

Weighted Timed Games: Positive Results with Negative Costs

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Smart Houses on a Grid (Jadevej Case)



Eight houses
Electric local grid

Each house:

- ▶ Solar panels
- ▶ Electric heating
- ▶ Storage of energy



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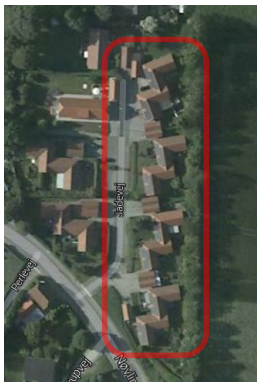
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Goal: for each house, optimize its behavior to reduce its energy bill

How to compute the expenses of a house?

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Solar panel ON

- Selling energy: $+2\text{€}/\text{t.u.}$
- Consumption: $0\text{€}/\text{t.u.}$
- Storing energy: $0\text{€}/\text{t.u.}$



Solar panel OFF

- Selling energy: $+2\text{€}/\text{t.u.}$
- Consumption: $-2\text{€}/\text{t.u.}$



Solar panel OFF

- Selling energy: $+1\text{€}/\text{t.u.}$
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+ fixed cost to start selling or buying energy

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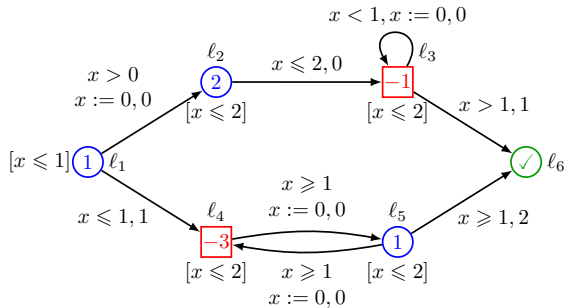
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Our contribution: Synthesize optimal behaviors in each phase by solving weighted timed games with a limited number of distinct rates

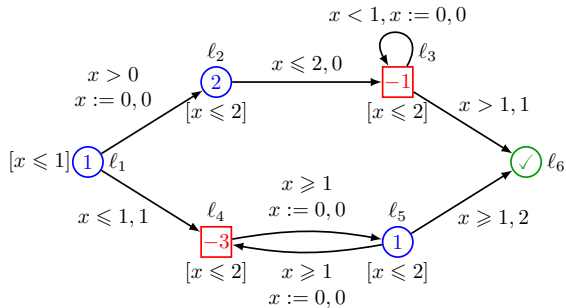
Weighted Timed Games



Timed Automaton
with partition of states
between 2 players
+ reachability objective
+ rates in locations
+ costs over transitions

Semantics in terms of
infinite game with weights

Weighted Timed Games

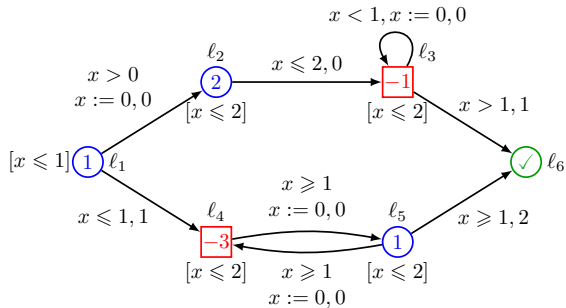


$(\ell_1, 0)$

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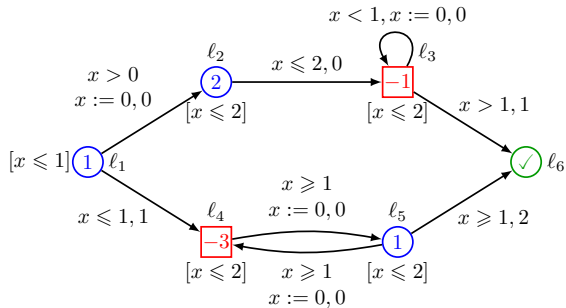


$$(\ell_1, 0) \xrightarrow{0.4, \searrow} (\ell_4, 0.4)$$

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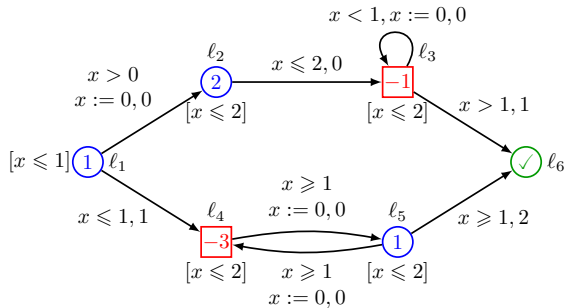


$$(\ell_1, 0) \xrightarrow{0.4, \searrow} (\ell_4, 0.4) \xrightarrow{0.6, \rightarrow} (\ell_5, 0)$$

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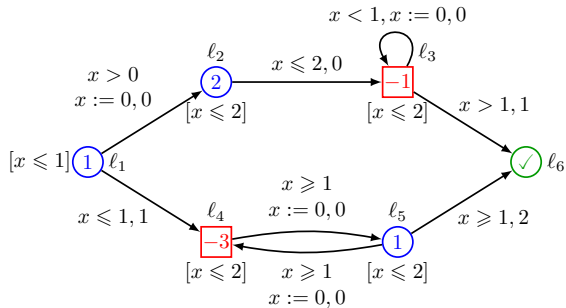


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Weighted Timed Games

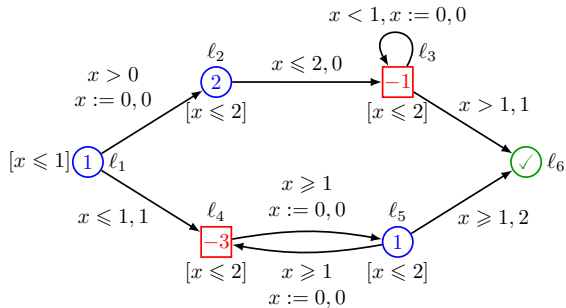


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$$(\ell_1, 0) \xrightarrow[0.4 + 1]{0.4, \searrow} (\ell_4, 0.4) \xrightarrow[-3 \times 0.6]{0.6, \rightarrow} (\ell_5, 0) \xrightarrow[+1.5]{1.5, \leftarrow} (\ell_4, 0) \xrightarrow[-3 \times 1.1]{1.1, \rightarrow} (\ell_5, 0) \xrightarrow[+2 \times 2 + 2]{2, \nearrow} (\checkmark, 2) = 3.8$$

Weighted Timed Games



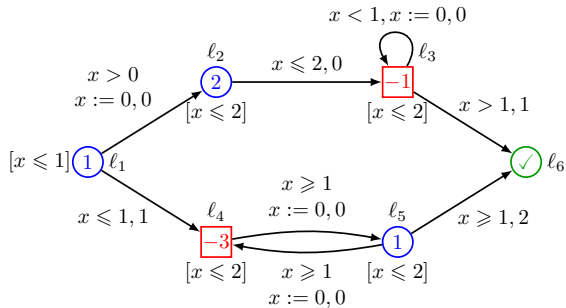
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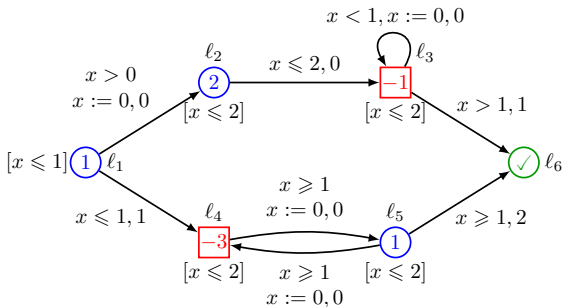
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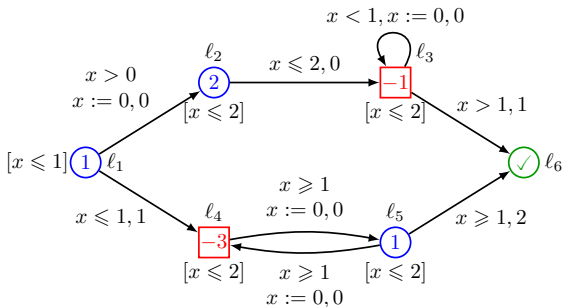
Weight of a play: $\begin{cases} +\infty & \text{if } \checkmark \text{ not reached} \\ \text{total payoff} & \text{otherwise} \end{cases}$

Strategies and objectives



Strategy for each player: mapping of finite runs to a delay and an action

Strategies and objectives

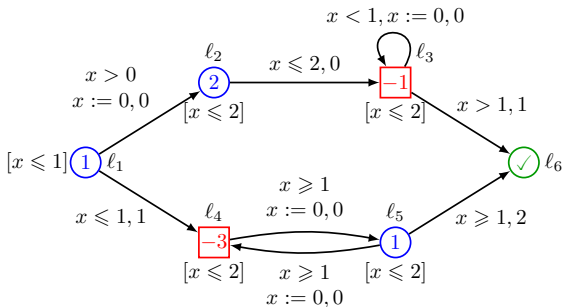


Strategy for each player: mapping of finite runs to a delay and an action

Goal of player \circ : reach \checkmark **and** minimize the cost

Goal of player \square : avoid \checkmark **or, if not possible,** maximize the cost

Strategies and objectives



Strategy for each player: mapping of finite runs to a delay and an action

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Main object of interest:

$$\overline{\text{Val}}(\ell, v) = \inf_{\sigma_{\circ} \in \text{Strat}_{\circ}} \sup_{\sigma_{\square} \in \text{Strat}_{\square}} \text{Wt}(\text{Play}((\ell, v), \sigma_{\circ}, \sigma_{\square})) \in \mathbf{R} \cup \{-\infty, +\infty\}$$

What player \circ can guarantee as a payoff? and design *good* strategies

State of the art

Decision problem: does there exist a strategy for player \bigcirc ensuring a weight not greater than a given constant?

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- ▶ One-player case (**Weighted timed automata**): optimal reachability problem is **PSPACE-complete**
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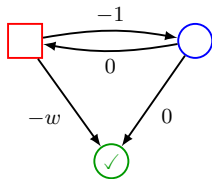
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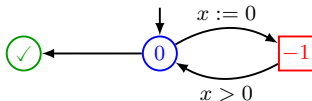
This talk: **One-clock weighted timed games with negative weights**

Why things are complex with negative weights? (even in weighted untimed finite games)

- ▶ Value $-\infty$: detection is as hard as mean-payoff. No hope for complexity better than $\mathbf{NP} \cap \mathbf{co-NP}$, or pseudo-polynomial
- ▶ Memory complexity
 - ▶ Player \circ needs memory

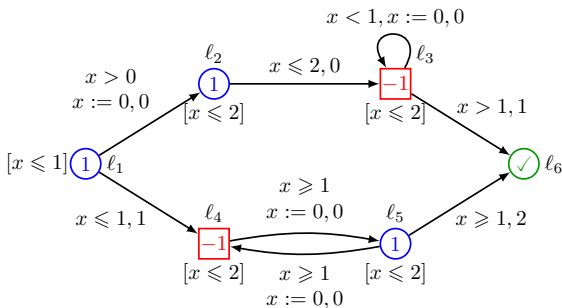


- ▶ Player \square needs infinite memory in weighted timed games



One-clock Binary Weighted Timed Games (1BWTG)

Assumption: rates of locations $\{p^-, p^+\}$ included in $\{0, +d, -d\}$ ($d \in \mathbf{N}$) (no assumption on weights of transitions)



- ▶ Techniques of [Bouyer, Cassez, Fleury, and Larsen, 2004, Alur, Bernadsky, and Madhusudan, 2004] not applicable, e.g., because of Zeno weights cycles
- ▶ Exponential algorithms of [Bouyer, Larsen, Markey, and Rasmussen, 2006b, Rutkowski, 2011, Hansen, Ibsen-Jensen, and Miltersen, 2013] not working because of presence of negative weights

Results

Theorem:

- ▶ Computation of the value $\overline{\text{Val}}(\ell, v)$ of states of a 1BWTG in pseudo-polynomial time
- ▶ Synthesis of ε -optimal strategies for player \circ in pseudo-polynomial time

Theorem: Non-negative case

In case of a 1BWTG with only non-negative weights, all complexities drop down to polynomial.

First idea: symetrize the point of view

Value for player \circ : $\overline{\text{Val}}(\ell, v) = \inf_{\sigma_{\circ} \in \text{Strat}_{\circ}} \sup_{\sigma_{\square} \in \text{Strat}_{\square}} \text{Wt}(\text{Play}((\ell, v), \sigma_{\circ}, \sigma_{\square}))$

Value for player \square : $\underline{\text{Val}}(\ell, v) = \sup_{\sigma_{\square} \in \text{Strat}_{\square}} \inf_{\sigma_{\circ} \in \text{Strat}_{\circ}} \text{Wt}(\text{Play}((\ell, v), \sigma_{\circ}, \sigma_{\square}))$

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Theorem: (continued)

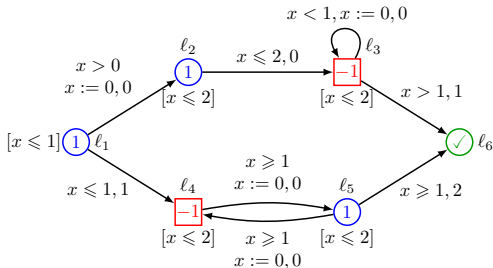
- ▶ 1BWTGs are determined: $\underline{\text{Val}}(\ell, v) = \overline{\text{Val}}(\ell, v)$
- ▶ Synthesis of ε -optimal strategies for player \square in pseudo-polynomial time (and polynomial in case of non-negative weights)

Sketch of proof

1. **Reduce the space of strategies in the 1BWTG:** restrict to uniform strategies w.r.t. timed behaviors
2. **Build a weighted finite games \mathcal{G}** based on a refinement of the region abstraction
3. **Study \mathcal{G}**
4. **Lift results of \mathcal{G} to the original 1BWTG**

1. Reduce the space of strategies

Intuition: no need for both players to play far from boundaries of regions



Regions: $\{0\}, (0, 1), \{1\}, (1, 2), \{2\}, (2, +\infty)$

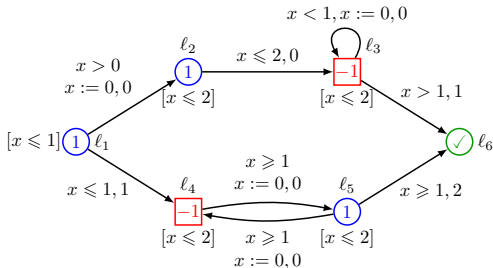
Player \circ wants to leave as soon as possible a state with rate p^+ , and wants to stay as long as possible in a state with rate p^- : so, he will always play η -close to a boundary...

Lemma:

Both players can play arbitrarily close to boundaries w.l.o.g., i.e., for every η

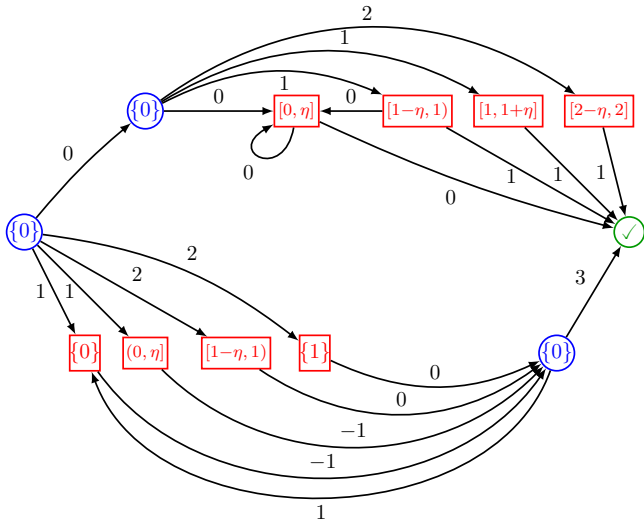
$$\underline{\text{Val}}^\eta(\ell, v) \leq \underline{\text{Val}}(\ell, v) \leq \overline{\text{Val}}(\ell, v) \leq \overline{\text{Val}}^\eta(\ell, v)$$

2. Weighted finite game abstraction

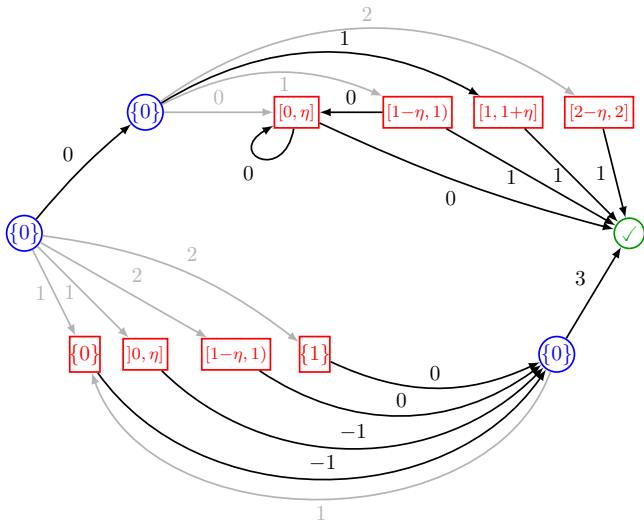


η -regions: $\{0\}, (0, \eta), (1 - \eta, 1), \{1\}, (1, 1 + \eta), (2 - \eta, 2), \{2\}, (2, +\infty)$

2. Weighted finite game abstraction



3. Study \mathcal{G} : values and optimal strategies



Optimal value: $\text{Val}_{\mathcal{G}}(\ell_1, \{0\}) = +2$ (for both players)

4. Lift results of \mathcal{G} to the original 1BWTG

Reconstruct strategies in the 1BWTG from optimal strategies of \mathcal{G}

Lemma:

For all $\varepsilon > 0$, there exists $\eta > 0$ such that:

$$\text{Val}_{\mathcal{G}}(\ell, \{0\}) - \varepsilon \leq \underline{\text{Val}}^{\eta}(\ell, 0) \leq \underline{\text{Val}}(\ell, 0) \leq \overline{\text{Val}}(\ell, 0) \leq \overline{\text{Val}}^{\eta}(\ell, 0) \leq \text{Val}_{\mathcal{G}}(\ell, \{0\}) + \varepsilon$$

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- ▶ So $\underline{\text{Val}}(\ell, 0) = \overline{\text{Val}}(\ell, 0)$, i.e., determination
- ▶ ε -optimal strategies for both players
 - ▶ Finite memory for player \bigcirc , because finite memory in weighted finite games
 - ▶ Infinite memory for player \square (even though memoryless in weighted finite games), because it needs to ensure convergence of its differences between the 1BWTG and \mathcal{G}
- ▶ Overall complexity: pseudo-polynomial (polynomial if non-negative weights) in the size of \mathcal{G} , which is polynomial in the 1BWTG (because 1 clock)

Summary and Future Work

Results

- ▶ 1BWTGs are determined: $\underline{\text{Val}}(\ell, v) = \overline{\text{Val}}(\ell, v)$
- ▶ Computation of the values in pseudo-polynomial time (and polynomial in case of non-negative weights)
- ▶ Synthesis of ε -optimal strategies for both players in pseudo-polynomial time (and polynomial in case of non-negative weights)
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Other results obtained in this context: undecidability results due to the presence of negative weights...

- ▶ Implementation and test of this algorithm for real instances
- ▶ Extensions to a richer model of priced timed games with negative weights: careful since players may need to play far from boundaries in case of 2 clocks, or 1 clock and 3 distinct rates...
- ▶ Consider other objectives, e.g., timed bounded restrictions, leading to decidability in some cases

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